CS378 - Autonomous Vehicles in Traffic II

Week 3a - Probability (Based on slides by Andrew Moore)

Real-Valued Random Variable

Boolean

- A can be {true, false}
- A: It will rain tomorrow

Discrete

- A can take a value from a given set
- A: number of years it will take for me to graduate

Continuous

- A takes all real values
- A: my distance to the wall

Probability

- The probability P(A = x) is the fraction of "worlds" in which A will turn out to be x.
- For boolean and discrete random variables, we define explicit probability values
- For continuous random variable, we define a probability density function (pdf)

For instance, the pdf of me being a certain distance from the wall could be a gaussian with a mean of 5 meters



Conditional Probability

 P(A = x|B = y) - The fraction of worlds (where B is y) in which A is x



P(F): probability of waking up with the flu = 1/40P(H): probability of waking up with a headache = 1/10P(H|F) = 1/2

 If A and B are independent boolean random variables, what is the conditional probability P(A|B)?

Inference

• What is the probability of having the flu if you wake up with a headache?



P(F): probability of waking up with the flu = 1/40P(H): probability of waking up with a headache = 1/10P(H|F) = 1/2

We need P(F|H) = P(F and H) / P(H)
 = (1/40 * 1/2) / 1/10
 = 1/8

But wait...

- What we did is an example of Bayes' rule
- P(F|H) = P(F and H) / P(H)
- i.e. P(F|H) = P(H|F) * P(F) / P(H)

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Week 3a - Expectation Maximization

Probability Density Function

- A probability density function gives an estimate of the distribution of output values *given* the input parameters.
- In the case of a normal distribution (i.e. gaussian), the pdf looks something like:

$$f_{\mu,\sigma^2}(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

• We can calculate the probability by taking the area under the curve:

$$P(X = x; \mu, \sigma) = f_{\mu, \sigma^2}(x)\Delta x$$



Samples

- Now, the *pdf* here defines how likely a given observation x is.
- Using this pdf, you can draw a number of samples from this distribution
- Aside: to get samples from an arbitrary pdf, use the cumulative pdf trick.

What do 10 samples look like?



Likelihood

- Now let's take the reverse scenario. I give you a distribution, and tell you that it is from a gaussian. What can you say about the input parameters that generated this data?
- Likelihood is defined as the probability some set of input parameters generated the given output:

 $P(\mu,\sigma|X) \quad \text{or} \ P(\theta|X)$

Likelihood

• We can define the likelihood of the same pdf by changing the arguments of the pdf: $P(\mu, \sigma | x) \propto f_x(\mu, \sigma^2)$

Maximum Likelihood Estimation

- Maximum Likelihood Estimation is the process by which we can determine the parameters that most likely explain the data.
- So what we are trying to do is find the theta which produces the maximum $P(\theta|X)$
- Since we just inferred that: $P(\theta|x) \propto P(x|\theta)$
- This means that MLE boils down to:

 $argmax_{\theta}(P(x|\theta))$ $argmax_{\theta}(logP(x|\theta))$

Let's take an example of MLE



• What is the maximum likelihood of this distribution?

A closed form solution perhaps?



Why did we not do well?

- Unfortunately 10 samples can sometimes be insufficient to capture the distribution!
- Maximum likelihood estimation just gave us the most likely answer that explained this data.
- What would have happened if we had more data points from the true distribution?

With a 1000 samples



- Mean: 0.044
- Standard Deviation: 1.003



MLE Summary

- Likelihood explains some a set of given data using different input parameters
- Likelihood values only mean something when compared against other such values
- Maximum likelihood estimation is producing parameters that *most likely* produced the data.
- Depending on the domain, we can sometimes do closed form analysis to obtain the MLE parameters.

And on to the tutorial...

• When all data is given, we can do MLE to obtain parameters.



Expectation Maximization

- When some of the data is hidden, it is no longer possible to calculate the MLE parameters directly
- EM is a maximum likelihood estimation technique when there is hidden data.
- These hidden variables are called latent variables.
- In the paper:
 - What data is hidden?
 - Why can't we do parameter estimation without this data?

How does EM work?

- Assume arbitrary values for the input parameters.
- Compute *soft* assignments for latent variables
- Calculate parameters using MLE now that you have all the observation data.
- Repeat till parameters no longer change.

How to compute assignments?

• For any given point of data (HTTTHHTHTH), we need to find the missing information (i.e. which coin did this data point come from?)

 x_i : HTTTHHTHTH

 z_a : $x_i \in coin_a$

 z_b : $x_i \in coin_b$

 Essentially we need to compute the probabilities of this data point belonging to each coin

 $p(z_a|x_i) \qquad \qquad p(z_b|x_i)$

How to compute assignments?

• We'll use Bayes' rule!!

$P(z_a x_i)$	=	$\frac{P(x_i z_a)P(z_a)}{P(x_i)}$
$P(z_b x_i)$	=	$\frac{P(x_i)}{P(x_i z_b)P(z_b)}$ $\frac{P(x_i)P(z_b)}{P(x_i)}$
$P(z_a x_i) + P(z_b x_i)$	=	1

Now since the coins were selected randomly

$$\implies P(z_a) = P(z_b) = 0.5$$

• This gives us:
$$P(z_a|x_i) = \frac{P(x_i|z_a)}{P(x_i|z_a) + P(x_i|z_b)}$$
$$P(z_b|x_i) = \frac{P(x_i|z_b)}{P(x_i|z_a) + P(x_i|z_b)}$$

How to compute $P(x_i|z_a)$

- P(x_i|z_a) is the probability of seeing a particular set of coin tosses given a particular coin
- If you roll an unbiased coin 10 times, are you more likely to get 10 heads in a row, or 5 heads in a row and then 5 tails in a row?
- If you roll an unbiased coin 10 times, are you more likely to see a total of 10 heads? or 5 heads and 5 tails?

How to compute P(z|a) and P(z|b)

• Let's take a look at the link I emailed you

http://math.stackexchange.com/questions/25111/how-does-expectation-maximization-work

Hard Assignments



Soft Assignments



Hard vs Soft Assignments

- Hard assignments mean a "greedy" strategy
- Soft assignments are more forgiving. Take the first assignment here:
- 0.45 x 2.2H, 2.2T = 2.8H, 2.8T
 The probability of this belonging to either coin is fairly close (i.e 0.45 and 0.55). It might not make sense to assign this to a single coin alone
- In practice both may work decently well.

So how did we do?

- The true values (without missing data) produced a result of 0.8 and 0.45
- Using EM, we converged at 0.8 and 0.45.
- Not bad!

Food for thought #1

• Would the output be different if we started with a different initial guess?

Food for thought #2

What if the true assignments were like this?
 What would θ̂_a and θ̂_b be



 How would the output of EM change? Would you say we still did well?

Food for thought #3

- Let's say if we repeated the experiment a 1000 times instead of 5 times. Would the output of EM always be closer to the true values or not?
 - Think about this one (or even better, code it up!). I'll discuss it on Wednesday

k-means

- k-means is a data clustering algorithm that is (almost) an example of EM. soft k-means is an example of EM
- I give you a data set of 1000 points in x,y space, and tell you to give me 5 clusters centers. How would you go about this problem?
- k-means approximates probabilities with distances

k-means

- Choose arbitrary cluster centers
- Assign each point to the closest cluster center (E step)
- Now that you have individual clusters, calculated the mean of each cluster (M step)
- Repeat this process until the cluster centers no longer change

soft k-means

- Choose initial cluster centers randomly
- Instead of hard assigning a point to a cluster center, *soft assign* it to all the cluster centers (E step)
- Use a *weighted mean* for each cluster to calculate the cluster center (M step)
- Repeat until convergence